

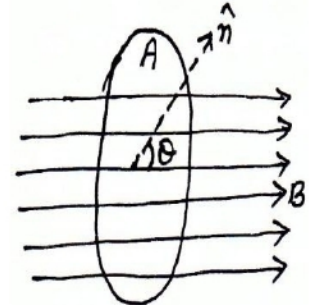
Unit-4(A) Electromagnetic Induction

1 Magnetic Flux: It is defined as the total numbers of magnetic lines of forces passing perpendicular to a given surface. It is a scalar quantity and denoted by:-

Φ or Φ_B .

i.e. $\Phi = \vec{B} \cdot \vec{A}$

or $\Phi = BA \cos \theta$



☞ Φ will be minimum if unit vector of surface is to applied magnetic field i.e. magnetic field is parallel to surface:-

as $\cos 90^\circ = 0 \Rightarrow \Phi = 0$

☞ Φ will be maximum if area vector is parallel to applied magnetic field in this case

$\theta = 0^\circ \Rightarrow \cos 0^\circ = 1$

Dimensional Formula of Magnetic Flux:

as $\Phi = BA = \frac{F}{qvB \sin Q} A$

or $\Phi = \frac{MLT^{-2}}{CLT^{-1}} L^2 = \frac{ML^2T^{-2}}{A}$

or $\Phi = [ML^2A^{-1}T^{-2}]$

SI unit of Magnetic Flux: The S.I unit of magnetic flux is Weber. One Weber is the amount of magnetic flux produced when one Tesla magnetic field act on body normally over an area of $1m^2$.

$1Wb = 1Tm^2$

CGS unit of Magnetic Flux: The c, g, s unit of magnetic flux is Maxwell (M_x). One Maxwell is the amount of magnetic flux produced when a uniform magnetic field of one gauss acts on a body normally on an area $1cm^2$.

$1M_x = 1Gcm^2$

Relation between Weber and Maxwell

$1Wb = 1T \times 1m^2 = 10^4G \times 10^4cm^2$

or **$1Wb = 10^8 Maxwell$**

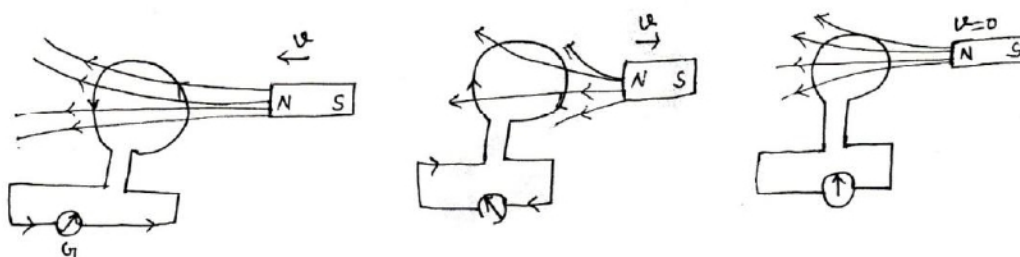
2. Electromagnetic Inductions:

The phenomenon of production of *emf* due to a change magnetic flux linked with a circuit is called electromagnetic induction. The generators and transformers are based on the principle of electromagnetic induction.

FARADAYS EXPERIMENTS:

Exp.-1: Induced emf with a stationary coil and moving magnet:

As shown in fig. take a coil connected to a sensitive galvanometer:-



Experiment:

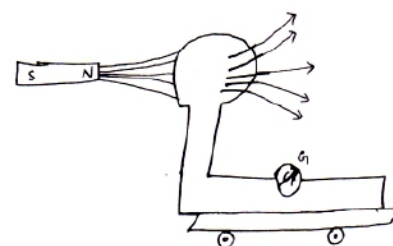
- (i) When the north pole of bar magnet is moved toward coil, the galvanometer shows a deflection, say to the right of the mark.
- (ii) When the north pole of the bar magnet is moved away from the coil, the galvanometer shows a deflection in opposite direction.
- (iii) When the magnet is held stationary, the galvanometer shows no deflection.
- (iv) If the South Pole is bringing toward coil the direction of current in coil becomes opposite.

Explanation or Conclusion:

When a bar magnet is moved toward or away from the coil, then the magnetic flux linked with the coil changes, as a result of which a current induces in the coil, which produce deflection in the galvanometer, but when there is no relative motion between coil and the magnet then there is no flux in coil, hence no current induces due to which galvanometer shows zero deflection.

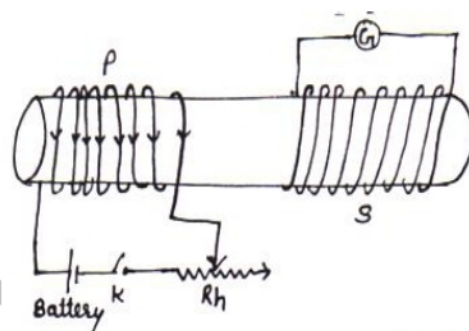
Exp.-2: Induced emf with a stationary magnet and moving coil:

Similar results are obtained as from exp-1 when the magnet is held stationary and the coil is moved. When the relative motion between the coil and the magnet is fast, the deflection in the galvanometer is larger and when the relative motion between coil and magnet are slow, the deflection in galvanometer is small. Hence greater is the rate of change of magnetic flux linked with the coil greater is the induced current set up in the coil.



Exp.-3: Induced emf by verifying current in the neighboring coil:

In Faradays third experiment there are two coil used. The first is called Primary coil connected to a battery through a key and Rheostat and the second coil are fixed near it called secondary coil connected to a galvanometer G. When constant current is flowed through the primary coil, then there is no any deflection in secondary coil but when current is increased or decreased in P coil then there is deflection in S coil.



As a current carrying coil behave as a magnet. Hence again this experiment is also conclude that a varying magnetic field produces current in the second coil.

From these experiments, we can conclude that:

- (i) Whenever the amount of magnetic field linked with a coil changes then any induces in the coil hence current induces.
- (ii) The higher the rate of change of magnetic flux linked with the coil, greater is the induced emf or current.

3. Law of Electromagnetic Induction: ^{M.Imp.}

There are two types of laws which govern the phenomenon of electromagnetic induction:

- (A) Faradays law which gives us the magnitude of induced *emf*.
- (B) Lenz's law which gives us the direction of induced *emf*.

(A) Faradays laws of electromagnetic induction:

First Law:-

When the magnetic flux linked with the current changes, an *emf* is induces which remains till there is change in magnetic flux in circuit. This phenomenon is also called electromagnetic induction.

Second Law:-According to Faradays second law, the magnetic of induced *emf* is equal to rate of change of magnetic flux linked with the circuit. *or*

According to this law, the *emf* induced in a circuit is directly proportional to rate of change of magnetic flux linked with the circuit.

I.e. suppose Φ , is the amount of magnetic flux at any time and Φ_2 is flux after t time then

$$\text{rate of change of flux} = \frac{\Phi_2 - \Phi_1}{t}$$

$$\text{from second law } e \propto \frac{\phi_2 - \phi_1}{t}$$

$$\text{Or } e = \frac{K(\phi_2 - \phi_1)}{t}$$

$$\text{Here } K = 1 \Rightarrow e = \frac{\phi_2 - \phi_1}{t}$$

$$\text{Or } e = \frac{d\phi}{dt}$$

Here -ve sign indicate that the emf induced in the coil will oppose the applied magnetic field or magnetic flux as according to Lenz law. Which is explained below?

Example 1: Flux associated with coil of resistance 10Ω and number of turns 1000 is 5.5×10^{-4} . If the flux reduces to 5.5×10^{-5} wb in 0.1 s. The electromotive force and the current induced in the coil will be respectively.

Sol: The induced e.m.f. in coil is $dE = -N \frac{d\phi}{dt} = \frac{N(\phi_1 - \phi_2)}{t_2 - t_1}$ Where N is the number of turns in the coil.

As Initial magnetic flux $\phi_1 = 5.5 \times 10^{-4}$ Wb. Final magnetic flux $\phi_2 = 5 \times 10^{-5}$ Wb

\therefore Change in flux $\Delta\phi = \phi_2 - \phi_1 = 5 \times 10^{-5} - 5.5 \times 10^{-4} = -50 \times 10^{-5}$ Wb

Time interval for this change, $\Delta t = 0.1$ sec \therefore Induced emf in the coil $E = -N \frac{d\phi}{dt} = \frac{-1000 \times -50 \times 10^{-5}}{0.1} = 5V$

Resistance of the coil, $R=10 \Omega$. Hence induced current in the coil is $I = \frac{E}{R} = \frac{5V}{10\Omega} = 0.5 A$

Example 2. A square loop of side 10 cm and resistance 0.5Ω is placed vertically in the east-west plane. A uniform magnetic field of 0.10 T is set up across the plane in the north-east direction. The magnetic field is decreased to zero in 0.70 s at a steady rate. Determine the magnitudes of induced emf and current during this time-interval.

Solution the angle θ made by the area vector of the coil with the magnetic field is 45° ,

The initial magnetic flux is $\Phi = BA \cos \theta = \frac{0.10 \times 10^{-2}}{\sqrt{2}}$ Wb Final flux, $\Phi_{\text{min}} = 0$

The change in flux is brought about in 0.70 s. the magnitude of the induced emf is given by $e = \frac{\phi_2 - \phi_1}{t} = \frac{10^{-3}}{\sqrt{2} \times 0.7} = 0.1mV$

And the magnitude of the current is $I = \frac{e}{r} = \frac{10^{-3}}{0.5} = 2mA$

Example 3. A circular coil of radius 10 cm, 500 turns and resistance 2Ω is placed with its plane perpendicular to the horizontal component of the earth's magnetic field. It is rotated about its vertical diameter through 180° in 0.25 s. Estimate the magnitudes of the emf and current induced in the coil. Horizontal component of the earth's magnetic field at the place is 3.0×10^{-5} T.

Solution Initial flux through the coil, $\Phi_{B(\text{initial})} = BA \cos \theta = 3.0 \times 10^{-5} \times (\pi \times 10^{-2}) \times \cos 0^\circ = 3\pi \times 10^{-7}$ Wb

Final flux after the rotation, $\Phi_{B(\text{final})} = 3.0 \times 10^{-5} \times (\pi \times 10^{-2}) \times \cos 180^\circ = -3\pi \times 10^{-7}$ Wb

Therefore, estimated value of the induced emf is, $\Phi e = N \frac{\Delta\phi}{\Delta t} = 500 \times \frac{6\pi \times 10^{-7}}{0.25} = 3.8 \times 10^{-3} V$

Current induced in the coil $I = \frac{\epsilon}{R} = 1.9 \times 10^{-3} A$

Example4: at certain location in the northern hemisphere, the earth's magnetic field has a magnitude of $42\mu\text{T}$ and points downward at 57° to vertical. The flux through a horizontal surface of area 2.5m^2 will be ($\cos 57^\circ = 0.545$)

Sol: The magnetic flux through any surface is $\phi = \vec{B} \cdot \vec{A}$ Using the formula of flux $\phi = BA \cos\theta$

We get the flux through the area as $\phi = BA \cos 57^\circ = 42 \times 10^{-6} \times 2.5 \times 0.545 = 57 \times 10^{-6} \text{Wb}$

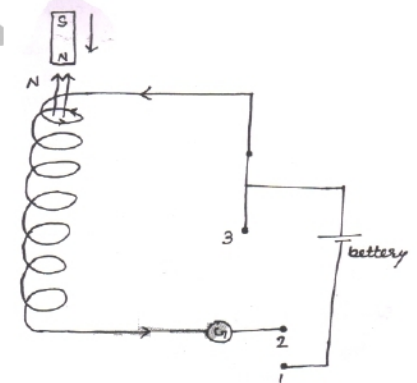
(B) Lenz Law:

According to Lenz law, the *emf* induced in a coil due to change in magnetic flux will oppose the change flux which is cause of its production.

Experimental Verification of Lenz Law:

The experimental set up used to verify Lenz law, is as shown in fig. firstly when we connect the terminal 1 & 2 then current flow in anticlockwise direction in the coil so that upper face of the coil behave as north pole and the deflection in galvanometer is toward right (says).

Now connect the terminal second and third. And bring North Pole toward the coil, and then we see that again the deflection in galvanometer is toward right. This shows that upper face of coil is North Pole. Again when South Pole is brought toward coil then deflection is toward left means upper face is south. Hence in each case the induced current always opposes the change in magnetic flux which produces it. This verifies the Lenz law.

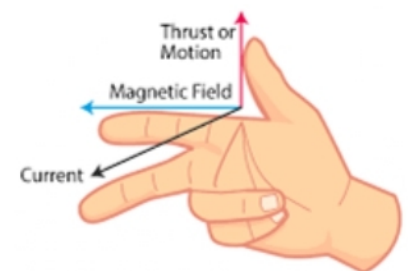


Show that Lenz laws obey law of conservation of Energy:

When a magnet is moved toward a coil then current induces in the coil here mechanical energy of motion of magnet is converted into electric energy and when motion is stopped then electric energy also becomes zero. Hence Lenz laws obey conservation of energy.

4. Fleming's Right hand rule: ^{M.Imp.}

This rule is used to find out the direction of induced current of a conductor moving in magnetic field. According to this rule, if we stretch, first finger, central finger and thumb in mutually \perp direction such that 1st finger is in direction of \vec{B} and thumb in direction of motion of conductor then central finger will give the direction of induced current.



QUESTION5. Difference between Fleming left hand and right hand rule?

- If a current carrying conductor is placed in magnetic field and we have to calculate direction of force than Fleming left hand rule is applied.
- And if current induces in a conductor when placed in magnetic field, than the direction of induced force is calculated by Fleming right hand rule.

5. Various Methods of Producing Induced emf:^{Imp}

There are three methods by which we can induce *emf* as $\Phi = BA \cos \theta$

- (i) By changing magnetic field B .
- (ii) By changing area A .
- (iii) By changing angle θ between magnetic field and normal to the surface.

As discussed below:

(i) By changing \vec{B} : As we have seen in faradays experiments that when we change magnetic field by moving magnet toward or away from a coil then *emf* induces in the coil. Larger is change in B more is *emf* induced.

(ii) By changing A :

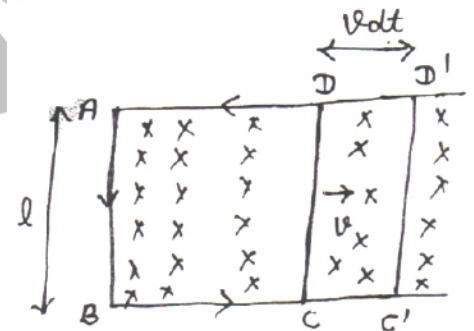
Consider a conductor CD of length l moving with a velocity v on a U shaped conducting rail situated in a magnetic field B . As conductor CD slides the area of the circuit changes. Then flux

$$d\Phi = B \times \text{change in area}$$

$$d\Phi = B \times l \times v dt$$

$$\text{Or } \frac{d\Phi}{dt} = Blv$$

$$\text{Or } e = \frac{d\Phi}{dt} = Blv$$



Hence by changing area flux can be produced i.e. *emf* can be induced. This induced *emf* is called motional *emf*.

(iii) Induced *emf* by changing relative orientation of coil and magnetic field. By changing angle between B and area of the coil, flux can be changed due to which *emf* induces into coil.

Example 6: The magnetic flux (ϕ) in a closed circuit of resistance 20Ω varies with time (t) according to the equation $\phi = 7t^2 - 4t$ where ϕ is in weber and t is in seconds. The magnitude of the induced current at $t=0.25$ s is

Solution: $\phi = 7t^2 - 4t \Rightarrow$ Induced emf: $|e| = \frac{d\phi}{dt} = 14t - 4$

\Rightarrow Induced current: $i = \frac{|e|}{R} = \frac{|14t - 4|}{20} = \frac{|14 \times 0.25 - 4|}{20}$ (at $t = 0.25$ s) $= 2.5 \times 10^{-2}$ A

6. Energy Consideration in Motional emf:

As we know *emf* induced in a conductor moving \perp to magnetic field is $e = Blv$

Or $I = \frac{e}{r} = \frac{Blv}{r}$

Also the force experienced by conductor in magnetic field is $F = BIl$

Or $F = BIl = B \left(\frac{Blv}{r} \right) l = \frac{B^2 l^2 v}{r}$

So power $P = F \cdot v = \frac{B^2 l^2 v^2}{r} \dots \dots \dots (i)$

Now conductor is pushed mechanically in the magnetic field, then mechanical energy per second is

$P = I^2 R = \frac{B^2 l^2 v^2}{r^2} r = \frac{B^2 l^2 v^2}{r} \dots \dots \dots (ii)$

Comparing eq. (i) and (ii) we can see that mechanical energy is converted into electrical energy and then thermal energy.

Example 7: A train is moving from south to north with a velocity of 90 km/h. The vertical component of earth's magnetic induction is 0.4×10^{-4} Wb/m². If the distance between the two rails is 1 m, what is the induced e.m.f. in its axle?

- (a) 1 mV (b) 0.1 mV (c) 10 mV (d) 100 mV

Solution: Induced emf = $Blv = 0.4 \times 10^{-4} \times 1 \times \left(90 \times \frac{5}{18} \right) = 10^{-3} \text{ V} = 1 \text{ mV}$

Example 8. A wheel with 10 metallic spokes each 0.5 m long is rotated with a speed of 120 rev/min in a plane normal to the horizontal component of earth's magnetic field H_E at a place. If $H_E = 0.4$ G at the place, what is the induced emf between the axle and the rim of the wheel? Note that $1 \text{ G} = 10^{-4} \text{ T}$.

Solution Induced $emf = \left(\frac{1}{2} \right) \omega B R^2 = \left(\frac{1}{2} \right) \times 4\pi \times 0.4 \times 10^{-4} \times (0.5)^2 = 6.28 \times 10^{-5} \text{ V}$

The number of spokes is immaterial because the emf across the spokes is in parallel.

Note that we have used $v = \omega r$. this gives $\varepsilon = \frac{1}{2} \times 1 \times 2\pi \times 50 \times (1)^2 = 157 \text{ V}$

7. Eddy Currents: or Foucault current:-^{M.Imp}

The current induced in the bulk piece of the conductors when the amount of magnetic flux linked with the conductor changes is called eddy current. This current is like eddy (whirlpool) in water also called Foucault current.

i.e. *eddy current* $i = \frac{\text{induced emf}}{\text{resistance}} = \frac{e}{r}$

or $i = \frac{-d\phi/dt}{r} \quad \left(\because e = \frac{-d\phi}{dt} \right)$

The direction of eddy current may be given by Lenz law.

Applications of eddy current:

(a) Electromagnetic damping:

In case of dead beat galvanometer, eddy current is used to overcome damping of coil provide a value of current without delay.

(b) Induction Furnace:

Eddy current is used to provide a higher temperature in furnaces to make alloys of metals. A high frequency A.C. current is passed through a coil surrounding the metals. The large eddy current induces metals due to which they melt.

(c) Magnetic Breaks:

In electric trains, strong electromagnets are situated in the train, just above the rail. When electromagnets are turned on, flux changes due to which eddy current are produced which opposes the motion of the trains.

(d) Electric Power Meter:

In electric power meter there is a rotating shiny metallic disc. This disc rotates due to eddy current produced by magnetic field due to A.C.

(e) Induction Motor:

In Induction Motor a rotating magnetic field produces strong eddy current in a rotor which starts rotating in direction of the rotating magnetic field.

(f) Eddy current also used in speedometers of automobiles and energy meter, in deep heat treatment of the human body.

Undesirable/harmful effects produced by eddy current:

- (i) It opposes the relative motion of bodies.
- (ii) Due to this there is lose of energy in from of heat.
- (iii) The excess heat produced in appliance may break their insulation and hence reduces their life.

Methods to Minimize eddy current:

To minimize eddy current, the metallic core should be taken in form of thin sheets in transformer, choke coil, motor etc. also each sheet should be insulated from each other and placed parallel to direction of magnetic field. By this we can reduce eddy current to a great extent.

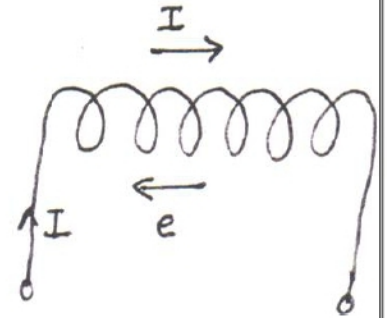
8. Self induction: ^{M.Imp}

It is the property of a coil by virtue of which it oppose the any change in the strength of current flowing through it by inducing an *emf* in itself.

Suppose at any instant of time, the magnetic flux linked with the coil is proportional to the amount of current I flowing through it.

i.e. $\phi \propto I$

Or $\phi = LI$



Where constant of proportionality L is called coefficient of self induction

If $I = 1 \Rightarrow \phi = L \quad \text{or} \quad L = \phi$

Hence *coefficient of self induction is equal to the amount of magnetic flux linked with the coil when unit current flows through the coil.*

Also $e = \frac{d\phi}{dt} = \frac{d(LI)}{dt}$

Or $e = -L \frac{dI}{dt}$

If $\frac{dI}{dt} = 1 \Rightarrow L = -e$

Hence *coefficient of self induction may also be defined as the amount of emf induced in the coil when rate of changes of current through the coil is unity.*

The unit of L is **Henry** As $L = \frac{-e}{di/dt}$

So $1 \text{ Henry} = \frac{1 \text{ Volt}}{1 \text{ Ampere /Sec.}}$

Hence *one Henry is the amount of self induction when one ampere current flowing per second through a coil produces 1 Volt emf.*

Dimensions of self induction: $L = \frac{e \, dt}{dI} = \frac{\text{Work}}{\text{Charge}} \cdot \frac{dt}{dI} = \frac{[M^1 L^2 T^{-2}][T]}{[AT][A]} = [M^1 L^2 T^{-2} A^{-2}]$

Example9: An average emf. of 0.20V appears in a coil when the current in it is changed from 5.0 an in one direction to 5.0

A in the opposite direction in 0.20 s. Find the self-inductance of the coil.

Sol: Using the formula $E = -\frac{LdI}{dt}$, we can find inductance of coil.

(i) The average change in current w.r.t. time t , $\frac{dI}{dt} = \frac{5.0A-5.0A}{0.20s} = -50 \text{ A / s.}$

(ii) Using formula $E = -\frac{LdI}{dt}$ we get $0.2V = 50 \times L \Rightarrow L = \frac{0.2}{50} = 4.0 \text{ mH}$

9. Self induction of a long solenoid:

As we know field a long solenoid having N turns is $B = \frac{\mu_0 NI}{l}$

Now magnetic flux through each turn of solenoid = $BA = \frac{\mu_0 NIA}{l}$

Now total magnetic flux through N turns = $\Phi = \frac{\mu_0 NIA}{l} \cdot N = \frac{\mu_0 N^2 IA}{l}$

$$\text{But } \Phi = LI \Rightarrow \frac{\mu_0 N^2 IA}{l} \Rightarrow L = \frac{\mu_0 N^2 A}{l}$$

$$\text{For a medium } \mu = \mu_0 \mu_r \Rightarrow L = \frac{\mu_0 \mu_r N^2 A}{l}$$

10. Mutual Induction: ^{M.Imp}

The phenomenon of production of induced emf in one coil due to change in amount of current in neighboring coil is called mutual induction.

Coefficient of Mutual induction:

At any instant of time the flux produced in the secondary coil is directly proportional to the amount of current passing through the primary coil.

$$\text{i.e. } \Phi \propto I$$

$$\text{or } \Phi = MI$$

Where M is a constant of proportionality called coefficient of mutual induction:

$$\text{If } I = 1 \text{ then } \Phi = M$$

Hence coefficient of mutual induction may be defined as the amount of magnetic flux induced in the secondary coil when one ampere or unit current flow through the primary coil.

$$\text{Also } e = \frac{-d\Phi}{dt} = -M \frac{dI}{dt}$$

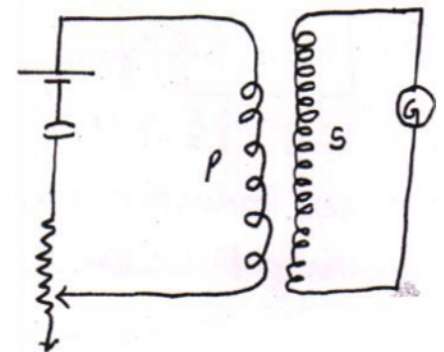
$$\text{If } \frac{dI}{dt} = 1 \text{ then } e = -M$$

Hence coefficient of mutual induction may also be defined as the amount of emf induced in the secondary coil when rate of change of current in primary coil is unity.

The S.I. unit of mutual induction is **Henry** As $M = \frac{-e}{dI/dt}$

One Henry is the amount of mutual induction when 1 Volt emf induces in the secondary coil by passing one ampere current per second through the primary coil.

- ✓ The coefficient of mutual induction depends upon shape, size, material, number of turn in the coil. Also on distance between the coils and their orientation



11. Mutual Induction of Two Long Co-axial Solenoid:

Suppose two long co-axial solenoids each of length l . again suppose n_1 and n_2 are the number of turns per unit length and r_1 and r_2 are the radius of solenoids.

If I_2 is the amount of current flowing in S_2 then $\Phi_1 = M_{12}I_2 \dots \dots \dots (i)$

Here M_{12} is mutual induction of 1 due to S_2

Also magnetic field in S_2 due to I_2 is $B_2 = \mu_0 n_2 I_2$

So flux through $S_1 = \Phi_1 = B_2 A_1 N_1 = \mu_0 n_2 I_2 \cdot \pi r_1^2 \cdot n_1 l$

or $\Phi_1 = \mu_0 n_1 n_2 \pi r_1^2 l I_2 \dots \dots \dots (ii)$

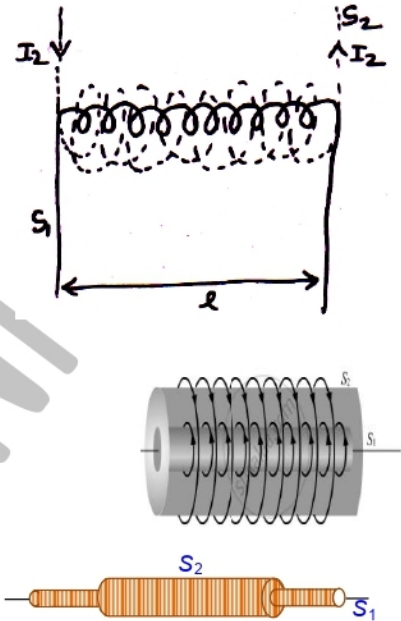
Comparing eq. (i) and (ii) $M_{12} I_2 = \mu_0 n_1 n_2 \pi r_1^2 l I_2$

$\Rightarrow M_{12} = \mu_0 n_1 n_2 \pi r_1^2 l$

Similarly we can show that $M_{21} = \mu_0 n_1 n_2 \pi r_1^2 l$

So $M = M_{12} = M_{21} = \mu_0 n_1 n_2 \pi r_1^2 l$

or $M = \mu_0 \left(\frac{N_1}{l}\right) \left(\frac{N_2}{l}\right) \pi r_1^2 l$ or $M = \frac{\mu_0 N_1 N_2 A}{l}$



This is the required expression for coefficient of mutual induction of two long co-axial solenoids.

12 Grouping of Coils:

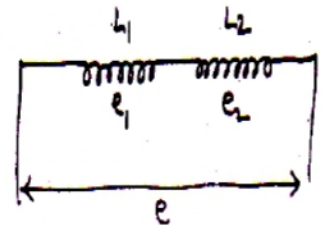
Coils in Series:-

Suppose two coils of coefficient of induction L_1 and L_2 are connected in series. Suppose I is the amount of current flowing per second in coils then total emf of coils is

$e = e_1 + e_2$

Or $L_s \frac{dI}{dt} = L_1 \frac{dI}{dt} + L_2 \frac{dI}{dt}$

Or $L_s = L_1 + L_2$



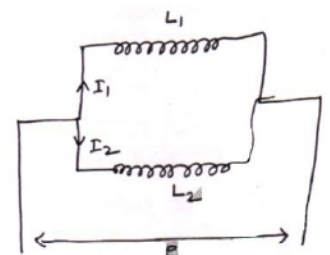
Coils in Parallel:-

Suppose two coils L_1 and L_2 are connected in parallel and e is the amount of emf in each will by the flowing of current I_1 and I_2 through the coils. Then total current through the coils is $I = I_1 + I_2$

Differentiating both sides we get $\frac{dI}{dt} = \frac{dI_1}{dt} + \frac{dI_2}{dt}$

Or $\frac{e}{l_p} = \frac{e}{L_1} + \frac{e}{L_2}$

$\Rightarrow \frac{1}{l_p} = \frac{1}{L_1} + \frac{1}{L_2}$



Hence grouping of coils is same to as that of grouping of the resistances.